

T-Question 3.1: Threads and Thread Models

a. What is the difference between a PCB and a TCB?

Solution:

- **Process control block (PCB)** *The PCB contains all information to implement a process as container of resources for threads (address space, open files, pending signals, etc.).*
- **Thread control block (TCB)** *The TCB holds thread-local management information such as (the pointer to) the stack of the thread and possibly the register set, when the thread is not running. There exists a TCB for each thread in a process.*
- b. The lecture and tutorials introduced two fundamental types of threads, depending on where the thread is implemented and where it executes. What are these two types? Give a short explanation for each.

Solution:

- **Kernel-level Threads (KLT)** *The TCB is implemented in the OS kernel. The kernel is thus fully aware of the threads and responsible for managing them.*
- **User-level Threads (ULT)** The thread is fully implemented in a user-space program or library (TCB, dispatching, scheduling, synchronization, etc.). The kernel is not aware of the threads.
- c. Give two disadvantages of the many-to-one thread model.

Solution:

- Blocking system calls block the entire application
- Cannot benefit from multiple CPUs/cores
- High implementation work (e.g., need to re-implement thread context, thread dispatching and scheduling, etc.)
- d. Explain the basic concept of a hybrid thread model.

Solution:

In a hybrid thread model (m-to-n model), m user-level threads are mapped to n kernellevel threads. The hybrid thread model combines the flexibility of a user-space thread library with the benefits of kernel-level threads (true parallelism, individual thread blocking).

e. Why does a switch to a thread of a different process normally take longer than a switch to a thread in the same process?

Solution:

When switching to a thread in a different process, the OS needs to perform a full context switch, which includes switching to a different PCB and address space. For a thread switch in the same process, most state can remain the same. Primarily, the current kernel stack and register state needs to be exchanged.

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